

Rotational Motion Equations

U6a

Everything we learned about translational motion applies to _____ motion. It is just that instead of measuring distance in _____ we measure _____ in _____. We can convert between the two systems using $d = \frac{v}{\omega}$. This also means $v = r\omega$ and $a = r\alpha$. Substituting these conversions into our 5 equations of _____ motion gives us 5 equations rotational motion.

Torque

Torque is the angular version of force. It has the formula $\tau = rF_T$. In other words, this means that the angular force (torque) is equal to the tangential _____ times the distance between where the _____ is applied and the pivot point (a.k.a. lever arm; separation of fulcrum and effort).

It is important to note that it is only the _____ component of a force that causes objects to rotate. The _____ component does not add or subtract to the net torque no matter how large it gets.

It is also important to note that, since torques involve rotation, a positive torque means the object _____ counterclockwise, while a negative torque tries to make _____ rotation happen. (Side note: Just like you can define up to be negative, you can reverse the meaning of the torque signs too, just be consistent.)

Instead of talking about the tangential component of the force, the book instead says the lever arm is the perpendicular _____ from the axis of _____ to a line drawn along the direction of the _____. This reduced-length lever arm is then multiplied by the full force.

All I have to say about this is

1. I don't like this definition. A lever is a physical object used for twisting: like a wrench or crow bar. The arm is the part you physically grab. So, imaginary geometrical construction lines are not involved.
2. Mathematically, shrinking the physical lever arm this way and multiplying by the full force is exactly the same thing as using the full-length lever arm and multiplying by the tangential portion of the force. So, why complicate life with the imaginary lines.

That said, the books way of defining torque is a clever shortcut for certain problems.

Gravity and Torque

Gravity is a force that can cause unbalanced objects to rotate. When gravity creates a torque, it behaves as though the entire force of gravity (aka _____) of the object pulls straight down at exactly the balance point of the object.

For your lab, the meterstick creates a counterclockwise torque. The mass creates a clockwise torque. When those two torques are _____ then the combination of the meterstick and the free-mass does not rotate and the system is _____. So, set the two torques equal to solve. Remember, r for the meterstick is the distance from the "naked" balance point to the new balance point (with the mass attached).

Rotational Equilibrium

U6b

- Similar to linear equilibrium, rotational equilibrium is when an object _____ or _____. This occurs when _____ = 0.
- Note: an object is in total static equilibrium if _____ and _____ are true. Some examples: a brick _____, an elevator _____, a windmill _____, a marble _____.
- Newton's 1st Law will thus become: An object at rest, in motion, or _____ will continue its _____ or rotation unless acted upon by a _____ or _____. Be certain to remember that a moving, rotating object _____ in static equilibrium.

Applying Newton's 1st Law to Static Equilibrium

- Linear equilibrium problems are always about choosing _____ and setting a sum of _____ equal to 0N. Rotational equilibrium problems require choosing a _____ to measure r from and setting all _____ = _____. Note: torque is a vector with directions of _____ (CCW) and _____ (CW). The _____ (a.k.a. axis of _____ or _____) or a stationary object is chosen to be wherever the math will be _____ (i.e. zero out non-essential torques).

Examples:

Rectangle in space (prove pivot point doesn't matter)

Teeter Toter

Scaffold

Boom

Ladder

Newton Gets Torqued

U6c

- Newton's 2nd Law states _____. Torque = _____. So, Newton's _____ Law becomes _____ = _____ => _____ = _____
- If there are multiple masses this becomes _____ = _____ = _____, where $I =$ _____ and is called the _____ (literally how _____ it is to _____ / _____ the _____ of an object).
- Note: Moment of Inertia depends on the _____ of _____.

Assorted Moments of Inertia (p. 230)

A number of small
mass lumps

Rod Rotated about Middle

Hoop or Cylindrical Shell

Rod Rotated about End

Disk or Solid Cylinder

Empty Soup Can (no lid)

Solid Sphere

Wagon Wheel

Conservation Of Energy (Again)

U6d

- To make a block slide across a smooth floor, you must _____ and do _____ on it.
This is what gives the block _____.
- To make a propeller spin, you must _____.
This is what gives the propeller _____.
- $KE_t = \frac{1}{2}mv^2$ Since $v =$ _____, $KE_r =$ _____ = _____ (for a single lump)
= _____ = _____ (for a distribution of mass)

- If you are sliding up a hill, you can use _____ for find out how far you slide. _____ = _____
- If you are rolling up a hill, this becomes
_____ = _____
(Note: You are rarely given both v and ω , so expect to use _____.)

Conservation Of Momentum (Again)

- To cause an object's momentum to change _____.
- To cause an object's angular momentum to change _____.
To make a propeller spin, you must _____.
- In the absence of a net force, conservation of momentum says $\underline{\quad} = \underline{\quad} \Rightarrow \underline{\quad} = \underline{\quad}$
(which is very boring for a single system).
- In the absence of a net torque, $\underline{\quad} = \underline{\quad} \Rightarrow \underline{\quad} = \underline{\quad}$ (which is much more interesting for a single system, because even though systems rarely loose _____, the pieces of can easily change _____).

Sliding Masses on Rod

Dropping Gum on a Hoop